

# Mixing Box MBE / MBP



Ferdinand Schad KG
Steigstraße 25-27
D-78600 Kolbingen
Telephone +49 (0) 74 63 - 980 - 0
Fax +49 (0) 74 63 - 980 - 200
info@schako.de
www.schako.de



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# **Description**

The mixing box type MBE/MBP consists of a housing with two round connection pipes and an integrated silencer unit for reducing flow generated noise. Two volumetric flow controllers are integrated, in order to allow the volumetric flow in ducts to be kept constant or variable or to be regulated using positive control  $V_{min}$ ,  $V_{max}$  or "CLOSED". It is used in two-duct air-conditioning systems, in which control and mixing can be carried out electrically or pneumatically, as desired. The measuring sensor used in the cold-air connection pipe and in the silencer unit is a flow-resistant measuring cross on which 12 measuring points have been distributed by the median line method, to allow a precise air flow measurement. A control flap is integrated in the round connection spigot to dampen and shut off. The first setting of values is done in-factory. With this factory setting, all mixing boxes are checked for correct functioning. The maximum deviation of the volumetric flows is +/- 5%, relative to the nominal volumetric flow V<sub>nenn</sub>, based on a calibration curve of 12 m/sec. At lower flow rates, the deviation in percent may in-

For the calibration of the controllers, a curve with a flow rate of 12 m/sec. is available. For constant-volume volumetric flow controllers, the  $V_{min}$  value will be set to the desired constant-volume value.

If the calibration curve must be changed on site, the controllers must either be recalibrated in-factory or the calibration curve must be changed on site by the customer service of Schako.

For the measurement of the effective pressure, Schako is using its measuring principle by means of a double measuring cross made of extruded aluminium profile, to which 12 measuring points have been attached on the pressure and suction side, respectively, by the median line method, in order to determine average values. In comparison with measuring rods or measuring orifices having fewer measuring points, this gives higher accuracy, allowing the inflow area required in front of the volumetric flow controller to be minimised (see page 5 - Installation Information).

When using the controllers in systems with heavy dust contamination, suitable filters must be connected upstream. For polluted air, use static membrane pressure sensors as transmitters. In this case, it is imperative to observe the notice sign regarding the mounting position. The mixing boxes are not suitable for air containing sticky and oily particles.

In all controller brands, the direction of rotation for opening is clockwise.

For maintenance, service, retrofitting, etc., inspection openings in sufficient number and size must be provided on site.

# Field of application

- for supply air systems
- for constant or variable volumetric flows
- Positive control V<sub>min</sub>, V<sub>max</sub>, or "CLOSED"
- Differential pressure range 250 1000 Pa
- for duct velocities:
  - MBE (electric) = 4 12 m/s
  - MBP (pneumatic) = 4 12 m/s
- for ambient temperatures of 0 50°C
  - Measuring air condition 0 50°C
  - 5 95% r.h., non-condensing
- Supply voltage for MBE (electric):
   24 V AC (19.2...28.8V) or 24 V DC (21.6...28.8V)
- Feed pressure for MBP (pneumatic): 1.2 ± 0.1 bar
- Design for spiral duct connection to DIN 24145
- With integrated silencer to reduce flow generated noise
- Additional acoustic cladding to reduce radiated noise available at an extra charge
- Additional silencer for further reduction of the flow generated noise available at an extra charge.

Only possible in connection with a connection frame (-AR)

#### Attention

The cold air connection piece must be insulated on site if there is a risk of condensate formation.

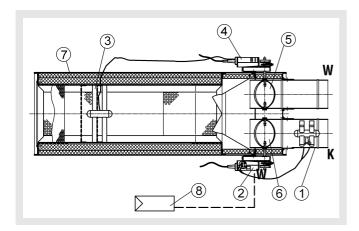
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#### Regulation

Mixing boxes are used in twin-duct air-conditioning systems. The unit mixes cold and hot air in such a way that the difference between the highest and the lowest temperature at the outlet of the device (low-pressure side) is less than 10%. Two control circuits independent of one another are formed, which allow the supply air to be controlled at a constant or variable flow rate. The differential pressure sensor for the cold air, with a measuring cross in the connection pipe (1), together with the cold air controller (2), forms a control circuit which is managed by the room temperature control (8) via a 0(2) - 10 V DC signal. The hot air control circuit comprising a differential pressure sensor, measuring cross (3) in the rectangular silencer unit (7) and hot air controller (4) is set to "constant" as standard and controls the total air volume by admixing the amount of hot air necessary for the sum of cold air and hot air to reach the total air volume. If the cold air volume exceeds the total air volume, the hot air control damper (5) will be completely closed. When cooling air demand decreases, the cold air control damper (6) is closed. The actual throughput of the air volume can be measured and evaluated via the U<sub>5</sub> signal of the controllers (in the case of electric mixing boxes).

Pneumatic mixing box MBP: Unlike the electronic mixing box MBE, this mixing box does not require a measuring cross (1) mounted in the round cold air connection pipe. A volumetric flow controller (PI or I controller) for activating the pneumatic actuators is adequate for control.



W = Hot air K = Cold air

Cold air either left or right as desired (shown on the left)

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# Installation

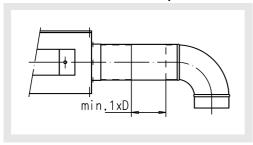
#### **Installation information**

To avoid unnecessary controller errors, the min. distances according to the following table / drawings must be observed. For combinations of several connection pieces or pieces with fire dampers or silencers, the larger minimum distances must be observed.

#### Distance to:

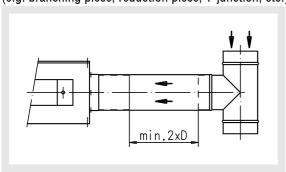
Connection piece with bend:	1 x D
Other connection pieces: (e.g. T-junction, branching piece, reduction piece, etc.)	2 x D
Fire dampers:	2 x D
Silencers:	2 x D

#### Distance to a bent connection piece

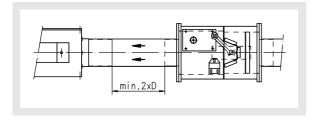


#### Distance to other connection pieces

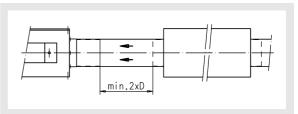
(e.g. branching piece, reduction piece, T-junction, etc.)



# Distance to a fire damper



#### Distance to a silencer



#### Construction

## Housing

- Galvanised sheet steel
- abrasion-resistant up to a duct velocity of 20 m/s
- Lined with mineral wool, perforated sheet cover.

#### Damper leaf seal

- made of PUR, silicone-free
- for airtight design to DIN EN 1751 Class 2 (NW100 only), Class 3 (NW125 - 400 only).

#### Guide baffle

- Galvanised sheet steel, perforated

#### Measuring cross

- Blades made of extruded aluminium profile
- Blade mount made of plastic (PA 6).

#### Silencer unit

- Lined with mineral wool, perforated sheet cover.

# Hot and cold air control damper

- galvanised sheet steel

#### Model

**MBF** - With electric control MBP - With pneumatic control ...-KR

- Cold air right in air flow direction

- Cold air left in air flow direction (standard) ...-KL

## **Accessories**

Connection frame (-AR)

- Galvanised sheet steel

Acoustic cladding (-DS)

- Galvanised sheet steel, with mineral wool lining

Rubber lip seal (-GD)

- Special rubber

Additional silencer (-ZS)

- Galvanised sheet steel, baffle with mineral wool lining (MWK) and optionally with perforated sheet cover (MLK).

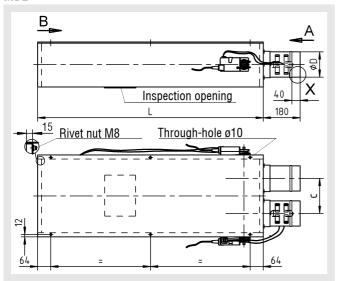
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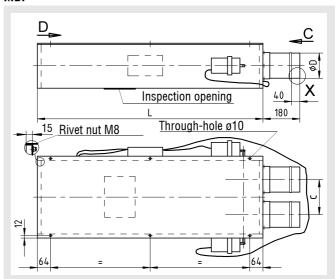
# **Models and dimensions**

# **Dimensions**

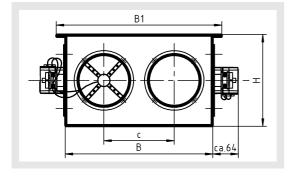
MBE



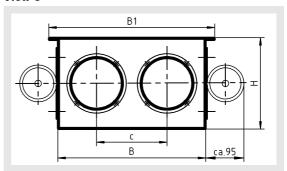
# MBP



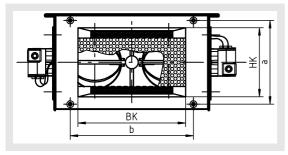
# View A



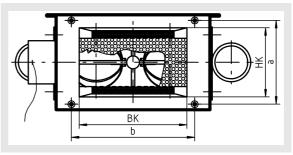
View C



# View B



View D



# **Available sizes**

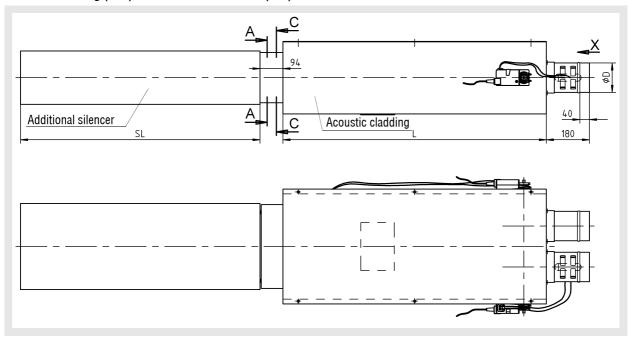
NW	В	B1	BK	Н	HK	L	øD	а	b	C
100	360	400	250	220	160	1100	98	194	286	178
125	480	520	370	230	170	1100	123	204	399	238
160	580	620	470	260	200	1400	158	234	504	288
200	700	740	590	290	230	1500	198	259	624	348
250	880	920	770	340	280	1500	248	309	804	438
315	1000	1040	890	440	385	1835	313	409	924	498
400	1400	1440	1290	490	430	1835	398	459	1324	698

For sizes 315 and 400, the housing consists of two parts mounted ex works.

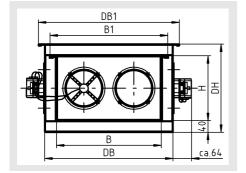


# **Dimensions of accessories**

Acoustic cladding (-DS) and additional silencer (-ZS)

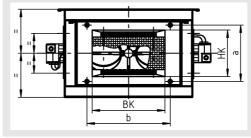


View X



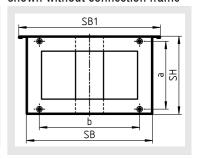
Section A-A

shown without connection frame

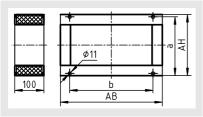


**Section C-C** 

shown without connection frame

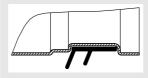


**Connection frame (-AR)** 



Rubber lip seal (-GD) Detail X





# **Available sizes**

NW	В	B1	DB	DB1	BK	Н	DH	HK	AH	AB	L	SL	øD	а	b
	=	=				=									
	SB	SB1				SH									
100	360	400	440	480	250	220	300	160	209	352	1100		98	194	286
125	480	520	560	600	370	230	310	170	219	465	1100	1000	123	204	399
160	580	620	660	700	470	260	340	200	249	570	1400	1000	158	234	504
200	700	740	780	820	590	290	370	230	274	690	1500		198	259	624
250	880	920	960	1000	770	340	420	280	324	870	1500		248	309	804
315	1000	1040	1080	1120	890	440	520	385	424	990	1835	1500	313	409	924
400	1400	1440	1480	1520	1290	490	570	430	474	1390	1835		398	459	1324

For sizes 315 and 400, the housing consists of two parts mounted ex works.



# **Technical data**

# **Volumetric flow range**

for MBE (constant or min/max)

NW	V		control volume	Cold air control variable			
Ø		elect	trical	electrical			
(mm)		v <sub>min</sub> (4m/s)	v <sub>max</sub> (12m/s)	v <sub>min</sub> (2 m/s)	v <sub>max</sub> (12 m/s)		
100	m <sup>3</sup> /h	106	319	53	319		
100	I/s	30	89	15	89		
125	m <sup>3</sup> /h	168	505	84	505		
120	l/s	47	140	23	140		
160	m <sup>3</sup> /h	279	836	139	836		
100	l/s	77	232	37	232		
200	m <sup>3</sup> /h	439	1317	219	1317		
200	l/s	122	366	61	366		
250	m <sup>3</sup> /h	690	2070	345	2070		
200	l/s	192	575	96	575		
315	m <sup>3</sup> /h	1101	3303	550	3303		
313	l/s	306	918	153	918		
400	m <sup>3</sup> /h	1783	5348	891	5348		
400	l/s	495	1486	248	1486		

#### for MBP (constant or min/max)

NW	V		control		trol variable
Ø		pneu	matic	pneu	matic
(mm)		v <sub>min</sub> (4m/s)	v <sub>max</sub> (12m/s)	v <sub>min</sub> (4 m/s)	v <sub>max</sub> (12 m/s)
100	m <sup>3</sup> /h	106	319	106	319
100	I/s	30	89	30	89
125	m <sup>3</sup> /h	168	505	168	505
123	I/s	47	140	47	140
160	m <sup>3</sup> /h	279	836	279	836
100	I/s	77	232	77	232
200	m <sup>3</sup> /h	439	1317	439	1317
200	I/s	122	366	122	366
250	m <sup>3</sup> /h	690	2070	690	2070
250	I/s	192	575	192	575
315	m <sup>3</sup> /h	1101	3303	1101	3303
010	I/s	306	918	306	918
400	m <sup>3</sup> /h	1783	5348	1783	5348
400	I/s	495	1486	495	1486

# Attention, the following specifications are important for programming the volumetric flow controllers:

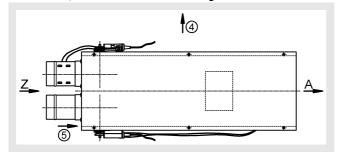
- This table merely specifies the complete measuring range of the controller (volumetric flow range)
- If the customer wants a calibration curve different from 12 m/s, it must be specified!
- When the air volume drops below the V<sub>min</sub> shown in the tables, the correct functioning of the volumetric flow controller is no longer guaranteed!
- If only one air volume is specified in the order (as  $V_{max}$  value), the volumetric flow controller will be delivered as variable volumetric flow controller. The  $V_{min}$  value will be set to the value specified in the catalogue.
- If only one air volume is specified in the order (as  $V_{min}$  or  $V_{konstant}$  value or without specifying a value), then the volumetric flow controller will be delivered as a constant volumetric flow controller. The volume specified in the order is set to the  $V_{min}$  value, and the  $V_{max}$  value is set to 100%.
- The air volumes can be changed using setting devices specific of the controller make, depending on the calibration curve set ex works.
- For the parameter setting of the control components (all controllers), an air density of 1.2 kg/m³ has been taken into account.
- Belimo compact controllers are elevation-compensated. They are calibrated ex works to the specific system elevation of the specified installation site.
- If no system elevation is given in the order, the controllers will be calibrated to the elevation of the delivery address.

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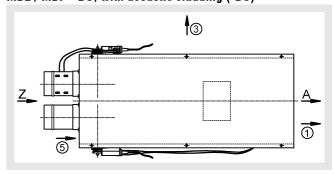


# **Sound values**

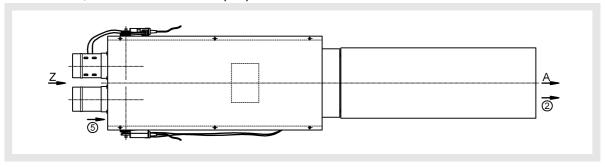
MBE / MBP, without acoustic cladding



MBE / MBP - DS, with acoustic cladding (-DS)



# MBE / MBP-ZS, with additional silencer (-ZS)



#### Insertion loss MBE / MBP

	NW			De	(dB/od	ct)			
		f <sub>m</sub> (Hz)							
		125	250	200	1000	2000	4000	8000	
cer	100								
ilen	125	17	24	34	38	36	28	21	
nals	160								
ditio	200	22	28	40	41	40	34	28	
without additional silencer	250								
	315								
wit	400								
-e-	100			43	44	42	33		
enc	125	23	30					27	
al Sil	160								
ions	200								
iddit	250	29	33	48	49	47	42	35	
with additional silencer	315							33	
*	400								

Insertion loss as the difference of the sound power levels measured with and without the mixing box.

- Z Supply air
- A Return air
- 1 Supply air flow generated noise without silencer
- 2 Supply air flow generated noise with silencer
- Radiated noise of supply air without acoustic cladding
- 4 Radiated noise of supply air with acoustic cladding
- 5 Flow generated noise in round duct for supply air

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Flow generated noise with / without additional silencer (-ZS)

NW	v <sub>k</sub>	V	V Static pressure difference						
	(m/s)	(m <sup>3</sup> /h)	[l/s]	250	Pa	500	Pa	1000	) Pa
				L <sub>WA</sub> [c	iB(A)]	L <sub>WA</sub> [c	iB(A)]	L <sub>WA</sub> [d	IB(A)]
				without additional		without additional		without additional	
				silencer	silencer	silencer	silencer	silencer	silencer
	3	80	22	26	19	30	23	34	27
100	6	160	44	29	22	33	26	37	30
	9	239	66	32	24	36	28	40	32
	12	319	89	38	30	42	34	46	38
	3	126	35	32	24	36	28	40	32
125	6	253	70	34	26	38	30	42	34
120	9	379	105	37	31	41	35	45	39
	12	505	140	41	33	45	37	49	41
	3	209	58	34	27	38	31	42	35
160	6	418	116	38	30	42	34	46	38
100	9	627	174	42	34	46	38	50	42
	12	836	232	44	36	48	40	52	44
	3	329	91	35	26	39	30	43	34
200	6	658	183	38	29	42	33	46	37
200	9	988	274	43	34	47	38	51	42
	12	1317	366	47	38	51	42	55	46
	3	517	144	36	26	40	30	44	34
250	6	1035	288	39	29	43	33	47	37
200	9	1552	431	44	33	48	37	52	41
	12	2070	575	49	38	53	42	57	46
	3	826	229	37	26	41	30	45	34
315	6	1651	459	40	29	44	33	48	37
010	9	2477	688	45	34	49	38	53	42
	12	3303	918	50	39	54	43	58	47
	3	1337	371	39	28	43	32	47	36
400	6	2674	743	42	30	46	34	50	38
400	9	4011	1114	46	34	50	38	54	42
	12	5348	1486	52	40	56	44	60	48

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# **Radiated noise**

with / without acoustic cladding (-DS)

NW	v <sub>k</sub>	١	ı			Static pressu	re difference		
	(m/s)	(m <sup>3</sup> /h)	[l/s]	250	Pa	500	) Pa	100	0 Pa
				L <sub>WA</sub> [c	iB(A)]	L <sub>WA</sub> [(	dB(A)]	L <sub>WA</sub> [	dB(A)]
				without acoustic	with acoustic	without acoustic		without acoustic	with acoustic
				cladding 40 mm	cladding 40 mm	cladding 40 mm	•	cladding 40 mm	cladding 40 mm
	3	80	22	35	26	40	31	45	36
100	6	160	44	39	30	44	35	49	40
	9	239	66	41	32	46	37	51	42
	12	319	89	43	34	48	39	53	44
	3	126	35	36	26	41	31	46	36
125	6	253	70	40	30	45	35	50	40
120	9	379	105	44	34	49	39	54	44
	12	505	140	46	36	51	41	56	46
	3	209	58	38	30	43	35	48	40
160	6	418	116	41	32	46	37	51	42
100	9	627	174	45	36	50	41	55	46
	12	836	232	49	39	54	44	59	49
	3	329	91	38	29	43	34	48	39
200	6	658	183	42	33	47	38	52	43
200	9	988	274	46	37	51	42	56	47
	12	1317	366	47	39	52	44	57	49
	3	517	144	39	30	44	35	49	40
250	6	1035	288	42	33	47	38	52	43
230	9	1552	431	46	37	51	42	56	47
	12	2070	575	48	39	53	44	58	49
	3	826	229	40	31	45	36	50	41
315	6	1651	459	44	35	49	40	54	45
310	9	2477	688	47	38	52	43	57	48
	12	3303	918	49	40	54	45	59	50
	3	1337	371	41	32	46	37	51	42
400	6	2674	743	45	36	50	41	55	46
400	9	4011	1114	48	39	53	44	58	49
	12	5348	1486	50	41	55	46	60	51

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# Technical data of the control components

#### Measured value collection and control function

The measured value collection is carried out via a flow-favouring double measuring cross. The measuring openings are distributed over the measuring cross according to the median line method. The pressure differential formed on the measuring cross is determined by means of a dynamic or static measuring sensor. The measured values are averaged to give an average value which represents a measuring quantity for the volumetric flow. The controller compares the actual value signal with the setpoint value and sends an output signal to the electric actuator which adjusts the controller deviation independent of pressure changes in the duct network.

The volumetric flow controllers of the Belimo make, types LMV-D3-MP Compact, VRD3-SO and VRP-VFP are delivered by SCHAKO as standard with the operating mode (Y signal,  $\rm U_5$  signal) 2-10 V DC. When activated by 2 V DC, the  $\rm V_{min}$  volume is controlled, the smallest possible  $\rm V_{min}$  volume that can be controlled can be seen from the "Volumetric Flow Range" tables. When the air volume drops below the  $\rm V_{min}$  shown in the tables, the correct functioning of the volumetric flow controller is no longer guaranteed!

#### Positive control damper "CLOSED"

Airtight sealing is achieved on site either via a positive control "CLOSED" by means of a switch or a relay, or via an actuator signal of 0 V DC applied to the input Y (all compact controllers equipped with the operating mode 2-10V DC). Accordingly, the drive will likewise close the flap in operating range 2 - 10 V DC (however, this does not apply to the operating range 0 - 10 V DC), and the VAV control will be inactive. To do so, it must be ensured that the actuator signal is < 0.1 V DC. This is why in rooms where defined pressures are active (e.g. laboratories), the flap should be closed via a digital on site switching contact.

If the Compact controllers of the Belimo make must be delivered with the operating mode 0-10V DC on customer request, please note that a positive control "CLOSED" can only be effected via a switching contact with diode.

If the compact controllers of the Belimo make are used together with the type VRP-VFP-300 in the master/slave mode or in parallel mode, then only the 2-10 V DC operating mode is usually possible.

## Positive control damper "OPEN"

Supports smoke extraction or is used as a safety position. The volumetric flow controller is in this case inactive, and the damper is driven to the mechanical open position. In this case, it is recommended using an actuator with spring return function (e.g. Belimo make, type VRD3, actuator type LF24-V). This ensures that the actuator flap will be driven into the defined "OPEN" end position also via an digital contact or in case of power failure.

## V<sub>min</sub> control to a minimum volumetric flow

Depending on requirement or by not assigning them, individual areas can be set to stand-by operation. In this way, minimum room flushing with greatly reduced energy expenditure is achieved.

# V<sub>max</sub> control to a max. volumetric flow

Individual or several rooms are supplied for a short period with a maximum volumetric flow. This allows, for example, a room through-ventilation or efficient heating to be effected.

#### **Continuous operation**

As a function of the continuous driving signal and the programmed operating range (0-10 V DC or 2-10 V DC), the volumetric flow controller will regulate the volumetric flow linearly between the setpoint values of  $V_{min}$  and  $V_{max}$ .

## **Constant operation**

If terminal 3 (Y driving signal) has not been assigned, the air volume set on the  $V_{min}$  potentiometer will be set to a constant volume.

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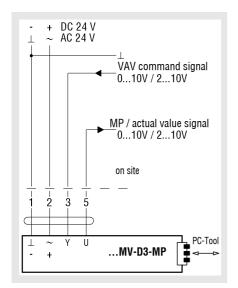


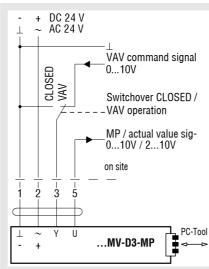
# **Circuit diagrams**

Circuit diagram standard controller Compact controller Belimo make LMV-D3-MP

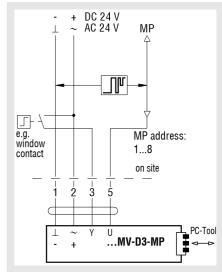
VAV with analogue command signal

# VAV with lock (CLOSED) Mode 2-10V DC





# MP bus activation with integrated switch



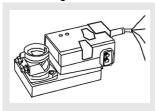
#### Lock mode (CLOSED)

In the 2 - 10 V mode, the following function can be carried with a 0 - 10 V signal:

Com- mand sig- nal Y	Volumetric flow	Function
< 0.1 V **	0	Damper CLOSED, VAV control inac- tive
0.22 V	V <sub>min</sub>	V <sub>min</sub> operating stage active
210 V	V <sub>min</sub> V <sub>max</sub>	Continuous operation V <sub>min</sub> V <sub>max</sub>

 $<sup>^{\</sup>star\star}$  Attention: Controller/DDC must be able to pull the command signal to 0 V.

# Cable designations

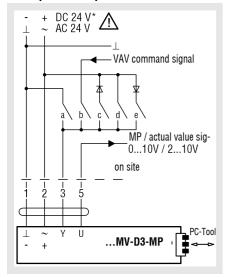


No.	Designation	Wire colour	Function		
1	<u></u>	black	⊥ - Ţ Feed		
2	+ ~	red	~ + \ \ AC/DC 24 V		
3	<b>→</b> Y	white	VAV / CAV command signal		
5	<b>→</b> U	orange	- Actual value signal - MP bus connection		

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# **CAV** operation / positive contacts



**Note:** Please ensure mutual locking of the contacts!

# **CAV function for MV-D3-MP**

Mode		010 V	010 V	010 V	010 V			
setting	210 V	210 V	210 V	210 V	210 V			
Signal	Т	010 V	~	۲	~			
Siyilai	-	210 V		+				
		<del></del> 0	<b>*</b>	$ \Diamond$	$\stackrel{\downarrow}{\Rightarrow}$			
Function	3	3	3	3	3			
Damper CLOSED	a) CLOSED		c) CLOSED*					
$V_{min}V_{max}$		b) VAV						
CAV - V <sub>min</sub>	everything open - V <sub>min</sub> active							
Damper OPEN					e) OPEN*			
CAV - V <sub>max</sub>				d) V <sub>max</sub>				

Contact closed, function active

Contact closed, function active, in mode 2 ...10 V only

Contact open

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<sup>\*</sup> not available for DC 24 V supply



# LED table of functions for LMV-D3-MP

Application	Function	Description / action	LED pat-	Adapta-		
			tern	Address	$\oplus$	LED 2 status
N1 operation	Status display	- 24V power supply o.k.	LED 1			
		- VAV-Compact ready for operation	LED 2			
S1 service function	Synchronisation	Synchronisation started by: a) Operating / service unit	LED 1			
		<ul><li>b) Manual trigger device at the VAV-Compact</li><li>c) Power ON behaviour</li></ul>	LED 2	Start		1.) → L
S2 service function	Adaptation	Adaptation started by: a) Operating / service unit	LED 1			
		b) Key on the VAV-Compact	LED 2	Start		2.) →
V1 VAV service	VAV service active	a) Press both keys «Adaptation» & «Address» simultaneously	LED 1			
	active	b) VAV service will be activated:	LED 2			
		<ul> <li>until 24V supply is switched off</li> <li>until both keys are pressed</li> <li>again</li> <li>after 2 hours have passed</li> </ul>		,		7
Lack of air		Damper opens as actual volume is too low	LED 1			
			LED 2			
	Target volume reached	Control circuit balanced	LED 1			
			LED 2			
	Air excess	Damper closes as actual volume is too high	LED 1			
			LED 2			
B1 bus operation	Addressing via MP master	a) Addressing has been triggered at the MP master	LED 1			
	(Acknowledge-		LED 2			
	ment at the VAV- Compact)	b) Press addressing key LED will switch to the communication display	LED 1			
	σοπράσε	as soon as the addressing process is complete.	LED 2	■ On event		MP communication
B2 bus operation	Addressing via MP master (with	Addressing at the MP master was triggered, LED will switch to the communication display	LED 1			
	serial number)	as soon as the addressing process is complete.	LED 2	■ Not addre ■	ess. 🖊	MP communication
B3 bus operation MP-PP display						
communication	Communication	ating / service unit	LED 2	MF	comm	nunication

green LED (power) is lit

yellow LED (status) is lit

yellow LED (status) is flashing

1.) Synch time

2.) Adaptation time



# Wiring diagram of alternative controller

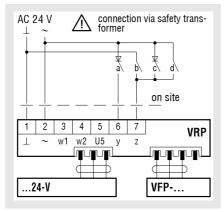
#### Universal controller Belimo make VRP-VFP300

#### **Connection diagram VRP**

#### AC 24 V connection via safety trans-former 0...20V\* - w2 DC 2...10V on site 3 4 2 5 6 1 **VRP** w2 U5 у VFP-... ..24-V

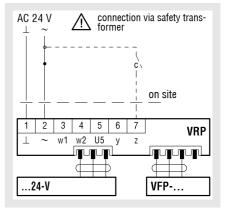
\* Phase crossover

# **Positive control VRP**



Function	a	b	C	d
CLOSED	_/_	1	_/_	/_
V <sub>min</sub>	_/_	\	۲	$\langle  $
V <sub>max</sub>	_/_	\	$\langle \cdot \rangle$	۲
OPEN	_/_	_/_	_/_	_/_

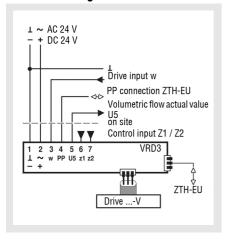
# Two-stage volumetric flow rate control VRP



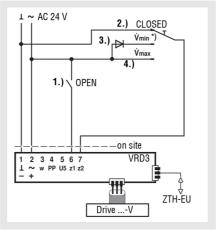
Function	a	b	C
V <sub>min</sub>	_/_	\ 	
V <sub>max</sub>	1	_/_	/_
V <sub>max</sub>	_/_	<u> </u>	/_
V <sub>max</sub>	_/_	_/_	7

#### Universal controller Belimo make VRD3-SO

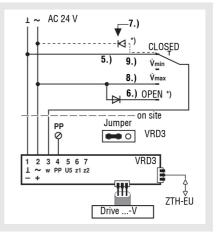
#### **Connection diagram VRD3-SO**



## **Positive control VRD3-SO**



# Two-stage volumetric flow rate control VRD3-S0



# Overview control signals / functions

Signal terminal / Function	<b>Priority</b>	GND	pos HW	neg HW	24 VAC	open
Forced contact Z1 - Terminal 6	1	-	OPEN 1.)	-	OPEN 1.)	-
Forced contact Z2 - Terminal 7	2	CLOSED 2.)	V <sub>min</sub> 3.)	-	V <sub>max</sub> <b>4.)</b>	-
Tool (PP-Cmd) -> ZTH-EU	3	CAV stages	(Auto, OPE	N, CLOSED,	V <sub>min</sub> , V <sub>ma</sub>	<sub>x</sub> , Stop)
Command signal w - Terminal 3 Jumper: VRD3	4	CLOSED <b>5.)</b> Mode: 2 10 V	OPEN 6.)	CLOSED <b>7.)</b> Mode: 0 10 V	V <sub>max</sub> <b>8.)</b>	V <sub>min</sub> 9.)

<sup>\*)</sup> requires AC 24 V power supply

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# Setting $V_{min}$ and $V_{max}$

The  $V_{min}$  and  $V_{max}$  operating volumetric flow settings can be made at the VRD3 in one of two ways.

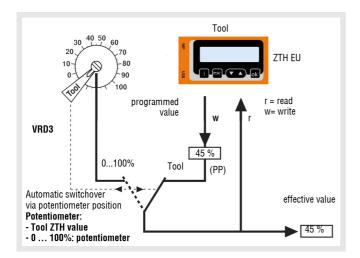
a) directly on the setting potentiometer (as with the VRD2)

 $V_{min} \, 0 \, \dots \, 100 \ \%$  of  $V_{nenn}$ 

V<sub>max</sub> 30 ... 100 % of V<sub>nenn</sub>

b) by means of the VAV setting device ZTH EU (PP Command) To write a value to the VRD3 by PP Command, both  $V_{min}$  und  $V_{max}$  potentiometers must be in the Tool position. When the potentiometer(s) are set to «Tool», with the ZTH EU connected, it may be necessary to refresh the menu by pressing the  $\blacktriangledown$ 

keys. The function can be seen from the following figure:



The  $V_{max}$  value must always be set higher than the  $V_{min}$ ; otherwise the VRD3 controller will run in the CAV mode with the  $V_{min}$  volume as setpoint.

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# Setting the operating potentiometers / calculation formulae

## Set value for V<sub>max</sub>

$$EW_{V_{max}} = \frac{V_{max}}{V_{nenn}} \times 100\%$$

The required volumetric flow that is to flow at the 10 V DC command signal at terminal 3 (w/Y) or with positive control  $V_{max}$  is set in % at the  $V_{max}$  potentiometer of the controller, the ZTH-EU device or PC-Tool. This value refers to the set  $V_{nenn}$  nominal volumetric flow.

# Set value for V<sub>min</sub>

$$EW_{V_{min}} = \frac{V_{min}}{V_{nenn} \text{ oder } V_{max}} \times 100\%$$

The required volumetric flow that is to flow at the 0 V DC command signal (operating mode 0-10 V DC) or at the 2 V DC command signal (operating mode 2 - 10 V DC) at terminal 3 (wY) or with positive control  $V_{min}$  is set in % at the  $V_{min}$  potentiometer of the controller, the ZTH-EU device or PC-Tool. This value refers to the set  $V_{nenn}$  or  $V_{max}$  volumetric flow (depending on controller type).

# Information regarding the set value V<sub>min</sub>

In the following controllers, V<sub>min</sub> refers to V<sub>max</sub>:

Make	Туре
Belimo	VRP-VFP

in the following controllers, V<sub>min</sub> refers to V<sub>nenn</sub>:

Make	Туре
Belimo	LMV-D3-MP, VRD3

## Calculation of the U<sub>5</sub> voltage value

# Operating mode: 2 - 10 V DC:

$$U_{5} = \frac{V_{\text{max}}}{V_{\text{nenn}}} \times 8V + 2V$$

$$V_{\text{max}} \text{ values}$$

$$V_{\text{min}} \text{ values}$$

$$V_{\text{min}} \text{ values}$$

# Operating mode: 0 - 10 V DC:

U<sub>5</sub> = 
$$\frac{V_{max}}{V_{nenn}} \times 10V$$

$$V_{max} \text{ values}$$

$$V_{min} \text{ values}$$

$$V_{min} \text{ values}$$

# Calculation of the $\mathbf{V}_{\text{nenn}}$ volumetric flow

$$V_{nenn} = EK \times F \times 3600$$

#### Attention:

The  $V_{nenn}$  value changes as a function of the set calibration curve.

EW (%) = Set value

EK (m/s) = Calibration curve

 $U_5$  (V DC) =  $U_5$  signal F (m<sup>2</sup>) = Area

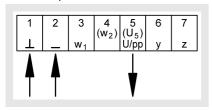
Depending on the required  $V_{max}$  volumetric flow, the calibration curve will be selected specifically by Schako during programming. This guarantees maximum accuracy of the actual value of the volumetric flow.

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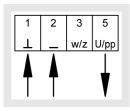


Actual value measurement via feedback signal  ${\rm U}_5$  using a voltmeter or PC-Tool

# Terminal assignment VRD3-SO / VRP-VFP



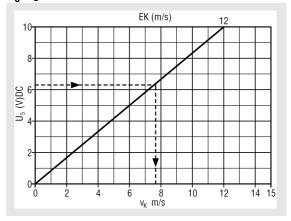
# LMV-D3-MP



Supply voltage: 24 V AC/DC (terminals 1+2) Measurement output 2 - 10 V DC (terminals 1+5) Measurement output 0 - 10 V DC (terminals 1+5)

The actual value signal  $\,\mathrm{U}_5$  is a real feedback of the volumetric flow actual value for monitoring and controlling the air throughput volume.

# U<sub>5</sub> signal 0-10 V DC



# **Example**

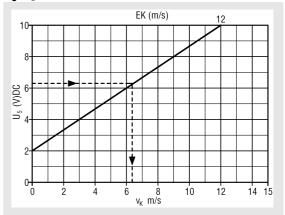
Assume: Measurement output signal  $U_5 = 6.3 \text{ V DC}$ 

Calibration value VRA-E = 12 m/sec

Measured value: Duct velocity = 7.6 m/s

Air volume: Duct velocity x area  $m^2$  x  $3600 = m^3/h$ 

# U<sub>5</sub> signal 2-10 V DC



# **Example**

Assume: Measurement output signal  $U_5 = 6.3 \text{ V DC}$ 

Calibration value VRA-E = 12 m/sec

Measured value: Duct velocity = 6.3 m/s

Air volume: Duct velocity x area  $m^2$  x  $3600 = m^3/h$ 

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# Technical data of controllers and motors Controller standard

#### LMV-D3-MP (make Belimo)

Dynamic pressure sensor, digital VAV controller and damper drive as communication-capable VAV-Compact solution

Measuring principle: Pressure reading with through-flow

Measuring range of the 2... ~ 450 Pa

sensor:

Supply voltage: AC 24 V 50/60 Hz; DC 24 V Functional range: AC 19.2...28.8 V; DC 21.6...28.8V

Power consumption: 2 W Dimensioning: 3.5 VA

Torque: min. 5 Nm at the rated voltage

Control function: VAV/CAV/Open-Loop;

Supply/return air or stand-alone operation;

master/slave parallel circuit;

Mixing box control

Setting range  $V_{min} = 0...100 \%$  of set  $V_{nenn}$  volumetric

 $V_{min}/V_{max}$ : flo

 $V_{max} = 20...100$  % of set  $V_{nenn}$  volumetric

flow

Command variable w/Y: DC 2-10 V (4...20 mA with 500  $\Omega$  input re-

(Input resistance min. sistance)

100 k $\Omega$ ) DC 0-10 V (0...20 mA with 500  $\Omega$  input re-

sistance)

adjustable DC 0...10 V

Setting range actual val- DC 2...10 V ue signal U<sub>5</sub>: DC 0...10V

MP bus function

Address in bus mode: MP 1 ... 8 (traditional operation: PP)
LONWORKS® / with BELIMO interface UK24LON

Konnex EIB: UK24EIB, 1 ... 8 BELIMO MP devices (VAV / flap drive/ valve)

DDC controller: DDC controller / PLC from different manu-

facturers, with integrated MP interface

Fan Optimiser: with BELIMO Optimiser COU24-A-MP

Sensor connection: Passive (Pt1000, Ni1000, etc.) and active

sensors (0...10 V), for example temperature, humidity, 2-point signal (switching

power 16 mA @ 24 V), for example switch,

presence detector

Protection class: III (safety extra low voltage)
Protection type: IP 54 (hose-connected)
EMC: CE according to 39/336/EEC

Measuring air and ambi- 0° C...+50° C. 5...95% rH. non-condensing

ent temperatures:

Storage temperature: -20° C...+80° C Sound power level: max. 35 dB (A)

Operation and service: plug-in via service socket / PC-Tool (from

V3.1) / ZTH-EU

Communication: PP/MP bus, max. DC 15V, 1200 baud

Connection: Cable, 4 x 0.75mm<sup>2</sup>, terminals

Weight: approx. 500 g

## **Controller alternatively**

#### VRP-VFP (make Belimo)

For static differential pressure control with separately available sensors VFP-100, 300 or 600

Measuring principle: Pressure measurement with metal mem-

brane

Measuring range of the 0...100 Pa, 0...300 Pa or 0...600 Pa

sensor:

Supply voltage: AC 24 V 50/60 Hz;

Power consumption: 1.3 W (incl. sensor VFP-..., without actua-

tor)

Dimensioning: 2.6 VA (incl. sensor VFP-..., without actua-

tor)

Command variable w: -

Command variable w1: DC 2-10 V (input resistance 100 k $\Omega$ )

Command variable w2: 0-20 V phase crossover (input resistance 8

 $k\Omega$ 

Operating range: DC 2-10 V Volumetric flow: DC 2-10 V

Actual value signal U<sub>5</sub>: Torque: Sound power level: -

## VRD3-SO (make Belimo)

with integrated dynamic differential pressure sensor

Measuring principle: Pressure reading with through-flow

Measuring range of the 2... ~ 300 Pa

sensor:

Supply voltage: AC 24 V 50/60 Hz; DC 24 V

Power consumption: 2 W

Dimensioning: 3.5 VA (without damper drive)

Command variable w: -

Command variable w1: DC 0-10 V (input resistance 100 k $\Omega$ )

Command variable w2: -

Operating range: DC 2-10 V (0-10V switch over via ZEV)
Volumetric flow: DC 0-10 V (for operating mode 0-10)
Actual value signal U<sub>5</sub>: DC 2-10 V (for operating mode 2-10)

Torque:

Sound power level: -

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Damper drives...24for VRP-VFP, VRD3-SO, VRP-STP, VRP-M

#### NM24A-V

Supply voltage: AC 24V 50/50 Hz / DC 24V of VR...,

ready to plug in

Power consumption/

Dimensioning: 3.5 W / 5.5 VA

Actuator signal: DC 6.0 V± 4V (of VR...)

Torque at the

rated voltage:

Min. 10 Nm

Running time for 90°

(or 95°): 150 s. Protection type: IP 54

Protection class: III (safety extra low voltage)

Sound power level: max. 35 dB (A)

#### **SM 24A-V**

Supply voltage: AC 24V 50/50 Hz / DC 24V of VR...,

ready to plug in

Power consumption/

Dimensioning: 4 W / 6 VA

Actuator signal: DC 6.0 V± 4V (of VR...)

Torque at the

rated voltage: 20 Nm

Running time for 90°

(or 95°): 150 s. Protection type: IP 54

Protection class: III (safety extra low voltage)

Sound power level: max. 45 dB (A)

#### LF24-V

Supply voltage: AC 24V 50/50 Hz / DC 24V of VR...,

ready to plug in

Power consumption/

Dimensioning: 6 W / 10 VA

Actuator signal: DC 6.0 V± 4V (of VR...)

Torque at the

rated voltage: Min. 15 Nm

Running time for 90°

(or 95°): Drive 150 s, spring return =16 s Protection type: IP 54

Protection class: III (safety extra low voltage)

Sound power level: Drive max. 45 dB(A) / Spring max. 62 dB(A)

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## **Functional check**

# VRD3-SO, VRP-VFP functional check

#### **Electric connection:**

Apply supply voltage 24 V AC ( $\pm 10\%$ ) to terminals 1 + 2. Is the polarity of the system neutral conductor correct?

 $\Rightarrow$  No: Check the wiring according to the diagram. Check transformer power.

→ Example: VRD3-SO (2.9 VA), VRP-VFP (2.6 VA), NM24-V (4.0 VA)

⇒ Yes: VR.. / drive ...24-V

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## VR.. / drive ...24-V:

Connect terminals 1+7. Does the drive move to the "CLOSED" position?

⇒ No: Check the direction of rotation switch of the drive.

→ Switch on drive is marked L/R or A/B.

 $\Rightarrow$  Yes:  $V_{max}$ 

∜

# V<sub>max</sub>:

Connect terminals 2+7. Does VR.. control to  $V_{max}$ ?

No: Check and compare the setting of the V<sub>max</sub> potentiometer with the technical data on the VAV machine.

> → If the drive moves to the "OPEN" position, and the maximum volume is not reached, then the duct pressure is too low.

 $\Rightarrow$  Yes:  $V_{min}$ 

∜

# V<sub>min</sub>:

Interrupt the terminal 3 and/or 4 command variable. Does VR.. control to  $V_{\text{min}}$ ?

 $\Rightarrow$  **No:** Check and compare the setting of the  $V_{min}$  potentiometer with the technical data on the VAV machine.

⇒ Yes: If required, restore interrupted connections (terminals 3+4).

#### Functional check during startup and service

If required, easily accessible setting potentiometers and connections allow set values and the correct operation of the mixing box to be reliably and quickly checked on site.

# LMV-D3-MP: Functional check

#### **Electrical connection**

Apply supply voltage 24 V AC ( $\pm 10\%$ ) to terminals 1 + 2. Is the polarity of system neutral conductor correct?

⇒ **No:** Check the wiring according to the diagram. Check transformer power.

→ LMV-D3-MP 5 VA

⇒ Yes: LMV-D3-MP / ZTH-EU

 $\parallel$ 

#### LMV-D3-MP / ZTH-EU:

Has the LMV-D3-MP been set to the correct operating mode? (Check using the connected ZTH-EU!)

No: Set operating mode on the selector switch of the ZTH-EU and save it in the LMV-D3-MP by pressing the Set key.

→ Operating modes: 0-10 V, 2-10 V

⇒ Yes: Drive

 $\Downarrow$ 

#### Drive:

Use the ZTH-EU to set operating mode 2-10 V and connect terminals 1+3 of the LMV-D3-MP.

Does the drive move to the "CLOSED" position?

⇒ No: Contact VRA manufacturer.

 $\Rightarrow$  Yes:  $V_{max}$ 

 $\prod$ 

# V<sub>max</sub>:

Connect terminals 2+3 of the LMV-D3-MP and disconnect  $\rm U_5$  connection to the ZTH-EU.

If the LMV-D3-MP controls to  $V_{\text{max}}\,$  - Check actual value signal  $U_5.$ 

No: Check the V<sub>max</sub> potentiometer on the ZTH-EU and compare the settings with the technical data on the VAV device.

→ If the drive moves to the "OPEN" position, and the maximum volume is not reached, then the duct pressure is too low.

 $\Rightarrow$  **Yes:** Set system-specific operating mode using the ZTH-EU.

# Functional check during startup and service

If required, easily accessible setting potentiometers and connections allow set values and the correct operation of the mixing box to be reliably and quickly checked on site.



# **Startup using PC-Tool**

Direct connection in the switch cabinet or socket (traditional application)

#### **ZTH EU as MP level converter**



#### **Description**

The ZTH EU is also a potential-free interface between the USB port of a PC and the Belimo MP bus. It is used to connect the Belimo PC-Tool directly to the MP bus or directly to a programmable MFT drive.

#### **Power supply**

The ZTH EU is supplied with power by the USB port. The MP bus voltage is obtained internally by means of DC/DC converter. This is why no external power supply is necessary.

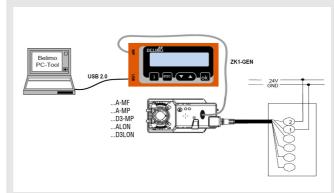
# Driver

To be able to work with the ZTH EU, a suitable driver must be installed on the PC. The driver can be downloaded from the Belimo website (download section). After installation of the driver, the ZTH EU device will log in to the PC as a virtual COM interface.

## Note

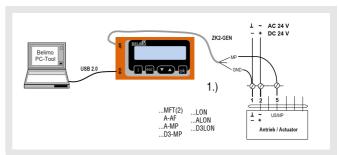
For connection to USB ports of PCs and BELIMO 24 V drives only (to safety extra low voltage SELV or US class 2 feeds).

# **Connection diagram 1**



Local connection via a service socket of the MF/MP or LON drive using a ZK1-GEN cable.

# **Connection diagram 2**



Local connection via a connecting cable of the MF/MP or LON drive using a ZK2-GEN cable.

1.) white = GND

green = MP

blue = not connected

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# Startup using the setting and diagnostic device ZTH EU (Belimo)



# **Short description**

The VAV setting device ZTH EU allows efficient testing of VAV and CAV installations. Installations fitted with the Belimo VAV controller can be simply adapted to the room and user requirements.

The VAV setting device ZTH EU replaces the previous setting device ZTH-GEN (2007-2014).

All standard Belimo VAV controllers with integrated PP communication (from 1992) that are sold in the EU can be set using the ZTH EU.

#### **Specifications:**

easy, quick setting of the VAV boxes parameters diagnostic function

one tool for all VAV units

voltage supplied by VAV controllers - no batteries required! service socket VAV / CR24 controller, PP connection includes connecting cable RJ12 6/4, 6-pin plug

New generation, MP bus tester

for functional test of MP bus

backward compatible with all Belimo PP / MP units from 1992 efficient handling, can be operated with one hand

Selection of stages for test (OPEN/CLOSE/MIN/MAX/STOP) Damper position indicator for diagnostics

Display of the setpoint / actual volume and  $V_{min/max}$  setting in  $m^3/s$  (I/s).

#### Keys / Display:



2 x 16-digit LCD with background lighting

▼▲ Forwards / Backwards Change value / status

OK Confirm input

ESC Cancel input/

Leave submenu/ Discard changes

i shows additional information if available

#### Connection:

Locally via service socket



#### **Dimensions:**

85x65x23 (WxHxD)

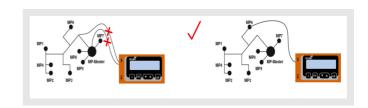
#### **Connection and supply**

Stand-alone operation:

Connection including supply takes place via the service socket at the VAV controller or via the terminals.

Bus operation:

The ZTH EU can be used in the following units while the bus is running if it is connected via the local service socket: VAV-Compact L/N/SMV-D3-MP, NMVAX-D3-MP, L/NMV-D3LON. With the VRP-M, L/NMV-D3-M and NMVAX-D3-MP, the MP-Bus must be disconnected when the service socket is used.



#### Restriction:

Direct connection in an MP network or via an MP-Bus master is not possible.

The ZTH EU comes with a quick start guide de/en to be affixed to the back of the unit.



#### **Smartphone - Belimo Assistant App**

The NFC antenna area of the VAV Compact is located between the Belimo or OEM logo and the NFC label.

Align NFC-capable android smartphone with loaded Assistant app on the VAV-Compact such that the two antennae are above one another.





The Belimo Assistant app can be downloaded from the Google Play Store.

#### NFC-capable devices:

 LMV-D3-MP, NMV-D3-MP, SMV-D3-MP and LHV-D3-MP with printed NFC label.

#### Non-NFC-capable devices:

- All devices without NFC label
- I MV-D3-MF
- LMV-D3LON and NMV-D3LON

#### **Controller selection**

Electric controller:	<u>Actuator:</u>
- 2x Belimo :	
- LMV-D3-MP	Compact (Standard)
- VRD3-S0	2x NM24A-V
- VRD3-S0	2x LF24-V
- VRP/VFP	2x NM24A-V
- VRP/VFP	2x LF24-V

The selection of each actuator (torque) depends on the housing dimensions.

Pneumatic controllers:	<u>Servo cylinder:</u>
- 1x Sauter :	
- RLP100 F916	1x AK 31 P2 F001 and 1x AK 31 P3 F001
- RLP100 F918	2x AK 31 P1 F001

## Accessories:

S1A/S2A, limit switch make Belimo, to fit all new compact controllers and actuators of make Belimo.

integrated potentiometer Belimo P1000 A

ZTH-EU for Belimo ...MV-D3-MP / PC-Tool for Belimo ...MV-D3-MP

# Maintenance and service Assembly and maintenance instructions

- 1. When the device is delivered, check whether the controllers are complete and delivered without damage. Complaints have to be communicated immediately and directly to the transporter and SCHAKO.
- 2. The mixing boxes must not be fastened to the regulation components, measuring crosses or the control dampers, but only to the housing.
- 3. The units must be carefully stored on site. They must be protected from dust, dirt and from direct weather effects.
- 4. The units must be assembled in a way in to allow inspection, meaning that the maintenance cover in the silencer part is freely accessible.
- 5. Assembly must be carried out by expert personnel, observing recognised technical rules and regulations.
- 6. For polluted air, the mixing boxes must be used with an integrated controller with static membrane pressure sensors. In this case, it is imperative to observe the notice sign regarding the mounting position. The mixing boxes are not suitable for air with greasy and sticky components.

## Zero adjustment of the static pressure sensors VFP-...

The pressure probe is based on a static pressure meter. Great care must be taken to ensure correct transport and correct assembly. The mixing box has been adjusted in-factory by the OEM manufacturer according to their mounting position. If the controllers are installed in a different position, the sensors can be adjusted as follows.

- 1. Sensor VFP-... must be installed.
- 2. Connect VFP-... to VRP and supply VRP with 24 V AC mains voltage.
- 3. Remove lid from VFP....
- 4. Move damper to the "OPEN" position.
- 5. Pull damper drive plug from the VRP.
- 6. Remove the pressure hoses from the connection pipes. **Attention!** Make a note of the (+) and (-) assignments.
- 7. The membrane position is considered balanced when both LEDs are dark (OFF). If the meter position is not balanced, one of the two LEDs will light up, and the position must be adjusted on the potentiometer in the VFP-...
- 8. Slowly turn the zero point adjustment of the potentiometer (non-painted potentiometer), until both LEDs are dark (OFF).
- 9. Assemble lid of VFP....
- 10. Reconnect pressure pipes as before (+) and (-).
- 11. Reconnect the plug of the damper drive.

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# Cleaning of the dynamic differential pressure sensor

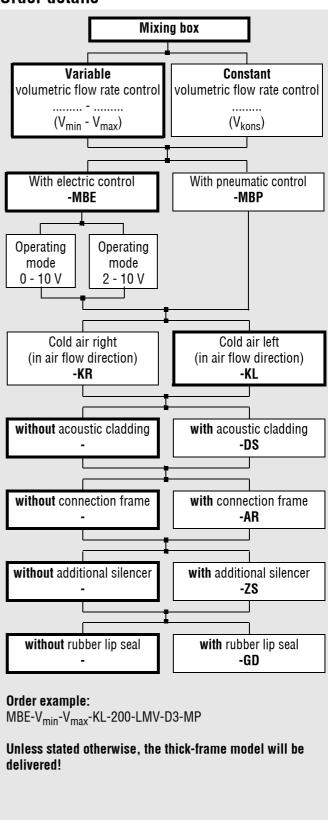
The dynamic differential pressure sensor integrated into the **LMV-D3-MP** and **VRD3-S0** requires little maintenance. However, if, depending on the degree of pollution of the air, unexpected volumetric flow deviations occur, then the following procedure is recommended.

- 1. Pull off the pressure hoses from the sensor connection pipe of the LMV-D3-MP or the VRD3.
  - Attention! Make a note of the (+) and (-) assignments.
- 2. Using a suitable hand pump, blow air into the (-) connection piece of the sensor (this will blow any dirt deposited inside the sensor out of the (+) connection piece).
- 3. Remove any dirt that may have formed from the connecting pieces and hose ends.
- 4. Reconnect pressure hoses, (+) and (-) as before.
- 5. Carry out a functional check of the controller.

# Legend

$f_{m}$	(Hz)	=	Octave centre frequency
$D_e$	[dB/Oct]	=	Insertion loss
$L_{WA}$	[dB(A)]	=	A-weighted sound power level
NW	(mm)	=	Nominal width
$U_5$	(V) DC	=	Measurement output (electric voltage)
$v_{K}$	(m/s)	=	Duct velocity
V	$(m^3/h)$	=	Air volume
V	[l/s]	=	Air volume
RE	(m/s)	=	Controller calibration value

# **Order details**



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# **Specification texts**

Mixing box for use in twin-duct air-conditioning systems, for spiral duct connection to DIN 24 145 with integrated volumetric flow controller for use in constant and variable volumetric flow, room and duct pressure regulation. With positive control  $V_{min}$ ,  $V_{max}$  or "CLOSED".

Consisting of a housing made of galvanised sheet steel lined with mineral wool, with a guide baffle made of perforated galvanised sheet steel. Housing containing two volumetric flow controllers, consisting of a round connection piece made of galvanised sheet steel with damper leaf made of galvanised sheet steel and silicone-free damper leaf seal for airtight design to DIN EN 1751, Class 2 (NW100 only), Class 3 (NW125 - 400 only), with measuring cross blades made of extruded aluminium profile, blade mount made of plastic (PA6). A special measuring cross allows position-independent mounting.

With electric control, control voltage 24 V AC, 50 / 60 Hz, temperature compensation of 10-40°C, wired and adjusted in-factory.

Product: SCHAKO type MBE

- With pneumatic control

Feed pressure 1.2 ± 0.1 bar

- Depressurised "CLOSED"
- Depressurised "OPEN"

Temperature compensation of 0 - 50° C

Product: SCHAKO type MBP

## Model

- Cold air right (-KR), in air flow direction
- Cold air left (-KL) in air flow direction (standard)

## Accessories (at an extra charge):

- Acoustic cladding (-DS) for reducing the radiated noise made of insulating material with sheet metal casing made of galvanised sheet steel.
- Galvanised sheet steel connection frame (-AR).
- Additional silencer (-ZS) made of galvanised sheet steel and baffle with mineral wool lining (MWK) and optionally with perforated sheet cover (MLK).
- Rubber lip seal (-GD), made of special rubber.

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